

Fixed-Sparsity Matrix Approximation from Matrix-Vector Products

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1. Problem

Structured Matrix Approximation

Find the best approximation from some structured class:

$$\min_{\hat{\mathbf{A}} \in \mathcal{S}} \|\mathbf{A} - \hat{\mathbf{A}}\|$$

- \mathcal{S} is rank- k matrices \rightarrow truncated SVD

Fixed-Pattern Sparse Approximation

Let $\mathbf{S} \in \{0,1\}^{n \times d}$ be a sparsity pattern:

$$\underset{\hat{\mathbf{A}}=\mathbf{S} \circ \hat{\mathbf{A}}}{\operatorname{argmin}} \|\mathbf{A} - \hat{\mathbf{A}}\|_{\mathrm{F}} = \mathbf{A} \circ \mathbf{S}$$

$$\mathbf{S} = \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} \rightarrow \text{just extract the diagonal}$$

- Banded, block diagonal, etc.

Matvec Access Model

- Queries: $\mathbf{x}_1, \dots, \mathbf{x}_m \mapsto \mathbf{A}\mathbf{x}_1, \dots, \mathbf{A}\mathbf{x}_m$
- E.g. $\mathbf{A} = \mathbf{B}^{-1}$
- (Adaptive? Transpose queries? ... You'll see)

Approximate Structured Matrix Approximation

- Compete with the best structured matrix approximation
- Find $\tilde{\mathbf{A}} \in \mathcal{S}$ such that

$$\|\mathbf{A} - \tilde{\mathbf{A}}\| \leq (1 + \epsilon) \min_{\hat{\mathbf{A}} \in \mathcal{S}} \|\mathbf{A} - \hat{\mathbf{A}}\|$$

- SVD \rightarrow RandSVD

Our Problem

“Approximate sparse approximation in the matvec access model”

Given

- $\mathbf{S} \in \{0,1\}^{n \times d}$
- matvec access to $\mathbf{A} \in \mathbb{R}^{n \times d}$

find sparse $\tilde{\mathbf{A}} = \mathbf{S} \circ \tilde{\mathbf{A}}$ such that

$$\|\mathbf{A} - \tilde{\mathbf{A}}\|_{\text{F}} \leq (1 + \epsilon) \|\mathbf{A} - \mathbf{S} \circ \mathbf{A}\|_{\text{F}}$$

What this is *not*

- Exact recovery
 - An exactly diagonal matrix can be recovered exactly with one matvec
 - Easier
- Compressed sensing (matrix version)
 - Unknown support
 - Harder

2. Upper Bound

Idea

- Sketch \mathbf{A} with m Gaussians

$$\begin{bmatrix} & & \\ & \mathbf{A} & \\ & & \end{bmatrix} \begin{bmatrix} | & & | \\ \mathbf{g}_1 & \cdots & \mathbf{g}_m \\ | & & | \end{bmatrix} = \begin{bmatrix} & & \\ & \mathbf{Z} & \\ & & \end{bmatrix}$$

- Solve a least squares problem for each row

$$\begin{bmatrix} a_{11} & ? & ? & ? \end{bmatrix} \begin{bmatrix} g_{11} & \cdots & g_{1m} \\ \vdots & & \vdots \\ g_{d1} & & g_{dm} \end{bmatrix} = [z_{11} \quad \cdots \quad z_{1m}]$$

Idea

- Sketch \mathbf{A} with m Gaussians

$$\begin{bmatrix} & & \\ & \mathbf{A} & \\ & & \end{bmatrix} \begin{bmatrix} | & & | \\ \mathbf{g}_1 & \cdots & \mathbf{g}_m \\ | & & | \end{bmatrix} = \begin{bmatrix} & & \\ & \mathbf{Z} & \\ & & \end{bmatrix}$$

- Solve a least squares problem for each row

$$a_{11} [g_{11} \quad \cdots \quad g_{1m}] + [\text{?} \quad \text{?} \quad \text{?}] \mathbf{G}' = [z_{11} \quad \cdots \quad z_{1m}]$$

Idea

- Sketch \mathbf{A} with m Gaussians

$$\begin{bmatrix} & & \\ & \mathbf{A} & \\ & & \end{bmatrix} \begin{bmatrix} | & & | \\ \mathbf{g}_1 & \cdots & \mathbf{g}_m \\ | & & | \end{bmatrix} = \begin{bmatrix} & & \\ & \mathbf{Z} & \\ & & \end{bmatrix}$$

- Solve a least squares problem for each row

$$[a_{11} \quad a_{21}] \begin{bmatrix} g_{11} & \cdots & g_{1m} \\ g_{21} & \cdots & g_{2m} \end{bmatrix} + [\text{?} \quad \text{?}] \mathbf{G}' = [z_{11} \quad \cdots \quad z_{1m}]$$

Upper bound

If \mathbf{S} has $\leq s$ non-zeros per row, then we need only $m = O\left(\frac{s}{\epsilon}\right)$ matvecs to solve w.h.p.

- Dimension free!
- Non-adaptive queries!
- Generalizes Hutchinson's diagonal estimator
 - [Batson & Nakatsukasa '22] [Dharangutte and Musco '23]
- Coloring / probing methods [Curtis Powell Reid '74] [Frommer Schimmel Schweitzer '21] [Schäfer Owhadi '21]
 - Worse even for exact case with doubly sparse \mathcal{S} : $m = \Omega(s^2)$
 - Beats us by $(m - s)/m$ for some banded matrices

Fact: if $\mathbf{G} \in \mathbb{R}^{m \times s}$ and $m \geq s + 2$ then $\mathbb{E} [\|\mathbf{G}^\dagger\|_F^2] = \frac{s}{m - s - 1}$ cf. [HMT 11]

3. Lower Bound

Hard Instance

Let

- $\mathbf{G} \in \mathbb{R}^{d \times d}$ have iid Gaussian entries
- $\mathbf{A} = \mathbf{G}^\top \mathbf{G}$ (Wishart)
 - Linear Regression, PCA, trace estimation
 - [Braverman et al. '20] [Simchowitz, Alaoui, Recht '18] [Jiang et al. '21]
- \mathbf{S} has between $s/2$ and s entries per row and column (e.g., block diagonal, banded)

Properties

- Symmetric, psd
- \mathbf{I} is special case
- Turns out, adaptive queries can't help much

A Wishart given matvec queries is still Wishart

Query $\mathbf{G}^\top \mathbf{G} \in \mathbb{R}^{d \times d}$ with m adaptive matvec queries

Then there exists $\Delta \in \mathbb{R}^{d \times d}$ and orthonormal \mathbf{V} s.t. the posterior distribution is

$$\mathbf{G}^\top \mathbf{G} \sim \mathbf{V} \left(\Delta + \begin{matrix} \overset{m}{\cdot} & \overset{(d-m)}{\cdot} \\ \cdot & \mathbf{G}_2^\top \mathbf{G}_2 \end{matrix} \right) \mathbf{V}^\top$$

[Braverman, Hazan, Simchowitz, Woodworth '20], used in several others

Anti-concentration of Wishart entries

- (From Berry-Esseen and anti-concentration of Gaussians)
- Let $\mathbf{G} \in \mathbb{R}^{k \times k}$ have Gaussian entries
- Impossible to accurately estimate $\mathbf{e}_i^\top \mathbf{G}^\top \mathbf{G} \mathbf{e}_j$ to accuracy better than \sqrt{k}

Anti-concentration of (rotated) Wishart entries

- (From Berry-Esseen and anti-concentration of Gaussians)
- Let $\mathbf{G} \in \mathbb{R}^{k \times k}$ have Gaussian entries
- Impossible to accurately estimate $\mathbf{u}^\top \mathbf{G}^\top \mathbf{G} \mathbf{v}$ to accuracy better than \sqrt{k}

Lower Bound

Let

- $\mathbf{G} \in \mathbb{R}^{d \times d}$ have iid Gaussian entries
- Let $\mathbf{A} = \mathbf{G}^\top \mathbf{G}$
- Let \mathbf{S} have $\Theta(s)$ entries per row/column (e.g., block diagonal)

Then:

$m = \Omega\left(\frac{s}{\epsilon}\right)$ queries are needed to achieve $(1 + \epsilon)$ error w.p. $\geq 5\%$

even if the queries are adaptive

In conclusion

The matvec query complexity of
approximate sparse approximation is

$$\Theta(s/\epsilon)$$

Open questions

- Beyond Frobenius norm
- Combining with “coloring methods”
- Other important classes: sparse + low rank, *hierarchical*, ...



Applications

- $f(\mathbf{A})$ where \mathbf{A} is banded [Park and Nakatsukasa 2023]
- $[\text{Cov}(\mathbf{X})]^{-1}$ where \mathbf{X} is drawn from a Gaussian Markov random field

Runtime

- Naively, must solve n least squares problems of size $m \times s$ so $O(nms^2)$
- For many sparsity patterns, you can reuse most work from the i th system to solve the $(i + 1)$ th system fast
- Embarrassingly parallel

Pros/cons of Coloring Methods

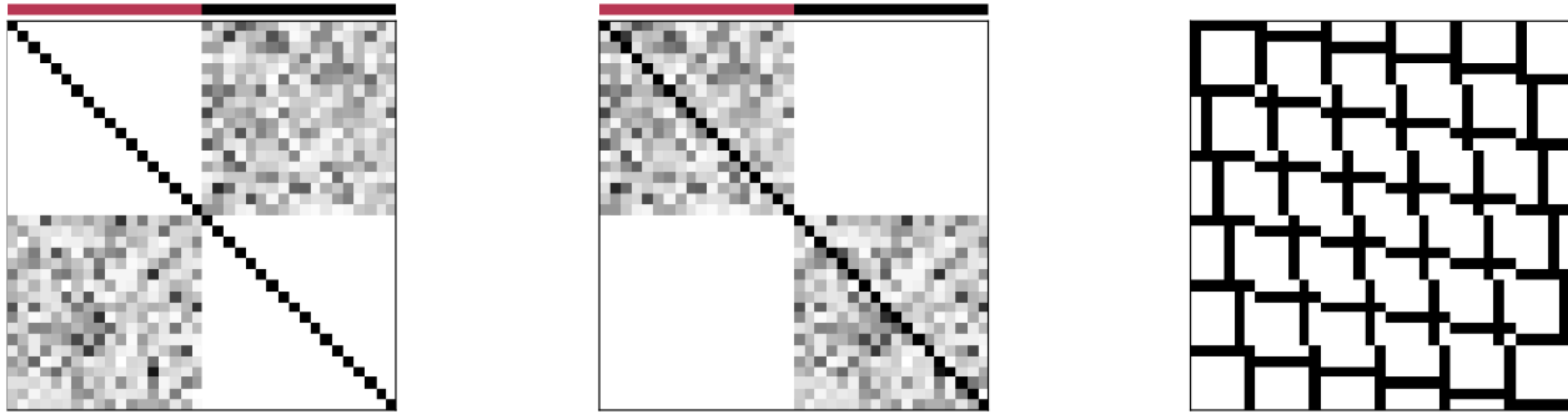


Figure 1: Left: Visualization of a matrix described in [Section 4.2](#) for which [Algorithm 1](#) is not the best method for recovering the diagonal (intensity indicates magnitude of entries of \mathbf{A}). In particular, the diagonal of the matrix can be recovered using exactly 2 queries, while [Algorithm 1](#) will require many queries to overcome the large noise in the off-diagonal blocks. Middle: Visualization of a matrix for which using the same colorings as the matrix on the left panel will not help. Right: Visualization of the hard sparsity pattern described in [Section 4.3](#) with $k = 10$. Here black pixels correspond to one and white pixels to zero. Note that while each row and column of the matrix has only $O(k)$ nonzeros, each pair of the k^2 columns has overlapping support.